



Kinetics of muscular function and architecture changes during of chronic low-frequency electrical stimulation

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Abstract

The effect of a 7-day “dry” water immersion (DI) with countermeasures (neuromuscular electrical stimulation - NMES) on the function and architecture of the human triceps surae muscle was studied in six healthy young men. During DI, subjects performed NMES muscle groups of both lower extremities every day. Internal architecture was measured in vivo by use of B-mode ultrasonography. The ankle was positioned at -15° , and 0 , $+15^\circ$, and $+30^\circ$ plantarflexion. At each position, longitudinal ultrasonic images of the medial and lateral gastrocnemius and soleus muscles were obtained while the subject was relaxed and performed 50 % maximal voluntary isometric contraction.

Introduction

Gravitational loading appears to be necessary for the maintenance of human lower limb skeletal muscle size and force [1]. Studies simulating microgravity have shown that exercise countermeasures can attenuate, but not completely prevent the loss of muscle mass and force [2,3]. The muscle groups most affected by exposure to microgravity appear to be the antigravity extensors of the knee and ankle [4]. Among these, the plantarflexors seem to be the most affected [4], likely due to their greater mechanical loading under normal gravitational conditions. Most notable after exposure to microgravity is a disproportionate loss of force as compared to that of muscle size [4], indicating that factors other than atrophy contribute to muscle weakness. The internal architecture of a muscle is an important determinant of its functional characteristics. There is a paucity of studies on the effects of disuse [5] or simulated microgravity [1,6] or real microgravity [7] on muscle architecture. The purpose of the present study was to investigate the internal architecture of the triceps surae [medial (MG) and lateral (LG) and soleus (SOL) muscles] in relation to the functional characteristics of the plantarflexors after 7 days of “dry” water immersion (DI) with exercise countermeasures [neuromuscular electrical stimulation (NMES)].

Materials and methods

Participants

We recruited six young men-volunteers (aged 22.8 ± 0.8 yr, 1.84 ± 0.1 m, and 79.3 ± 4.2 kg, mean \pm s.e.m). Selection of subjects was based on a screening evaluation that

consisted of a detailed medical history, complete blood count, urine analysis, resting and cycle ergometer electrocardiogram, and a panel of blood chemistry analysis, which included fasting blood glucose, blood urea nitrogen, creatinine, lactic dehydrogenase, bilirubin, uric acid, and cholesterol, as well as an evaluation of their physical state using a bicycle ergometer stress-test. Continuous, gradually increasing work in the bicycle ergometer at a constant pedaling rate of 60 rpm over 3 min with initial load of 50 W was specified; the load of subsequent “steps” was increased by 25 W; achievement of submaximal heart rate was the criterion for work termination.

All of the subjects were evaluated clinically and considered to be in good physical condition. No subject was taking medication at the time of the study, and all subjects were nonsmokers and with no neurological disorders participated. All subjects gave written informed consent in accordance with the Declaration of Helsinki. The experimental protocol was approved by the Institute of Bio-Medical Problems Ethic Committee.

“Dry” water immersion

To simulate microgravity the DI model has been used [8]. This model seems to be a useful method for ground based investigations. As it has been shown in prevision studies [9] a close similarity exists between the effects of short time real microgravity and immersion. However, the dimension of these changes is different. The alterations during and after immersion are more marked than those of equal duration spaceflights.

Briefly, the subject was horizontally positioned

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(a angle which make the body and horizontal line, e.g. 5° head-up position) in a special bath in a “suspended” state (the law of Archimedes), on special water-proof highly elastic fabric film, which acted only as an insulation between the skin and the water. There was no bed to support the subject's body. The folds of the water-proof material came together with water along the mid-line of the subject's body. Water temperature was constant (33.4° C) and maintained automatically at this level throughout the experiment. The exposure duration was 7-day and the subjects were kept under medical observation throughout the exposure. During the 7-day DI, the subjects remained in the experimental (horizontal) position continuously for all activities including voiding, and eating.

Neuromuscular electrical stimulation

NMES is applied to 4 muscle groups of both lower extremities. “Dry” electrodes (Ltd. «Axelgaard», USA) are placed on the skin above the quadriceps femoris muscles, the hamstrings, the tibialis anterior, the peroneal, and the triceps surae muscles. The synchronous stimulation of antagonistic muscle groups prevents unwanted joint movements. The NMES-training is performed during 3 hours per day with 1 s « on » and 2 s « off » trains at intensity levels of 20-30% of maximum tetanic force and a frequency of 25 Hz. The electrical stimulus was provided by the «STIMUL LF-1» stimulator (Russia). The technical equipment consists of electrode trousers carrying stimulation electrodes for the 12-channels, and 2 interconnected 6-channel stimulators caned on a belt. During DI, subjects executed a NMES-training during 3 hours per day with 1 s « on » and 2 s « off » with a frequency of 25 Hz and amplitude of stimulus from 0 up to 45 V for training. Used biphasic rectangular by 1 ms pulse width. After initialization procedure, the system begins automatic training. NMES-training of muscles of the examinee was carried out directly in a bath. The intensity level stimulation is determined by a threshold of bearableness of subjects.

NMES-training continued for six days, during which daily five days on end (from Monday to Friday inclusive) including one day of rest (Saturday). Duration of NMES-training was 3 hours/day. Each subjects instructed “*increase amplitude stimulation pulse during training*”.

Measurement of Maximal Voluntary Contraction Torque.

All subjects were instructed to abstain from food for 2 hours before testing, from caffeine for 4 hours before testing, and from exercise for 12 hours before testing. Before isokinetic testing was conducted, subjects pedaled a cycle ergometer at a workload of 25–50 W at a cadence of 60–80 rpm for 5 min. Standard joint-specific warm-up procedures were followed and consisted of five submaximal repetitions and two to three maximal repetitions. After the warm-up, subjects rested at least 2 min. Strength tests were performed such that subjects exerted a maximal effort in only one direction for each set of repetitions.

After a full warm-up, isometric ankle extension torque of the subjects' right legs was tested at joint angular velocities of 0°/s-1 using a Isokinetic Dynamometer (Biodex System 4 PRO™, Biodex Medical Systems, Shirley, New York, USA). Participants were seated upright in the Biodex dynamometer chair with their trunk positioned and secured to the seatback with waist and shoulder belts to ensure consistent positioning and minimal movement. The hips were positioned to 90° with the thigh and the knee angles at 45° flexed and the ankle was in the 90° joint angle were taken to determine the plantarflexion torque. The lateral malleolus of the right foot was aligned with the axis of rotation on the Biodex dynamometer (Biodex Medical Systems, N-Y). The

foot was fastened to the footplate with inelastic straps that were firmly secured behind and on the underside of the footplate to prevent heel lift. When heel lift occurred or torque did not return to baseline protocol was stopped and repeated after 3–5- min rest. Subjects performed three sets of four repetitions of maximal isometric ankle extension at an angular velocity of 0°/s-1 with a 2-min resting period between contractions unless the third trial exceeded one of the two first ones by more than 10%. In that case an additional trial was performed. The participants were instructed to grip the side handles to help stabilize the trunk.

Each subject was instructed to exert maximal effort in only one direction and in every movement when performing a test; no verbal instruction was provided during testing. Two min rest separated the sets. Isometric of peak torque at 0°/s-1 (maximal voluntary contraction – MVC) were recorded for each subject. The contractile properties of muscles were determined 2 days before the start of DI and 1 day after the end of DI.

Measurement of Muscle Architecture

Subjects performed a series of isometric plantarflexion contractions on an isokinetic dynamometer Biodex (Biodex Multi-Joint Systems, Shirley, N-Y, USA) at ankle angles of 0° (neutral ankle position: the footplate of the dynamometer perpendicular to the longitudinal axis of the tibia). Before the strength measurements, muscle thickness, pennation angles and fascicle length of the right TS muscle were measured in vivo by B-mode ultrasonography (SonoSite MicroMaxx (SonoSite MicroMaxx, USA)). All measurements were carried out with the knee joint flexed at 90°. To perform TS muscle ultrasound, a participant's foot was relatively rigidly fixed to a special platform, which allowed the ankle angle to be set at –15° (plantar flexion), 0° (neutral anatomical position), +30° (plantar extension). The MG, and LG, and SOL muscle architecture was assessed in vivo at rest and its change before and after 3 weeks DI, in the sagittal plane using B-mode ultrasonography, a linear 7.5-MHz electronic transducer with a 60-mm field of view at the proximal levels 30 % of the distance between the popliteal crease and the center of the lateral malleolus [10]. The linear array probe was coated with water-soluble transmission gel to provide acoustic contact without depressing the dermal surface. The ankle joint was fixed at –15° (plantar flexion), 0° (a neutral position), +30° (plantar extension). The knee joint was positioned at 0° (full extension). Ultrasound images were captured at the required time point and stored for subsequent analysis. Before measurements, the subjects were laid on a couch for 20 min to allow osmotic fluids to shift [11]. During measurements, the subjects were laid supine with the knees fully extended and muscles relaxed. The MG, and LG, and SOL muscle fibre fascicle length and pennation angle (defined as the angle of insertion of fascicles into the deep aponeurosis) were measured using digitizing software (Image J, 1.47v, National Institute of Health, Maryland, USA) before and after DI. The fascicle pennation angle (θ_f) was measured from the angles between the echo of the deep aponeurosis of each muscle and interspaces among the fascicles of that muscle [12]. The length of fascicles (L_f) across the deep and superficial aponeurosis was measured as a straight line [12]. This has been recently reported as a valid method of fascicle length estimation [13]. Images were collected and analysed by the same investigator.

After performance in the passive condition, the subject was encouraged to perform maximal voluntary isometric plantar flexion (active condition), and torque output was recorded. Each subject was then asked to maintain contractions for at least 2-3s at 50 % of MVC at the neutral ankle position (0 deg). Subjects

were given visual feedback of the target and elicited force on a computer screen. Shorter fascicle lengths and steeper fascicle angles in the active compared with the passive condition show internal shortening of fascicles by contraction. From these parameters, the ΔL_{muscle} was estimated by the following equation:

$$\Delta L_{\text{muscle}} = L_r \cos \Theta_r - L_f \cos \Theta_f, \text{ where}$$

L_r and L_f are fascicle lengths in rest (passive) and active conditions (50 % MVC);

Θ_r and Θ_f are fascicle angles in rest (passive) and active conditions, respectively.

Statistics

Data are presented as the mean values \pm standard error of the mean (SE). Differences in pennation angles, fibre lengths and thicknesses between rest and 50% MVC and between different ankle angles were tested using two-way analysis of variance tests. Tukey's test was used to determine significant difference between mean values. One-way analysis of variance (ANOVA) was used for comparison of muscle thickness, pennation angles, and fibre lengths. A level of $p < 0.05$ was selected to indicate statistical significance.

Results

Changes in maximal muscle strength

After the 7-day DI with application by NMES-training, maximal plantar flexion torque by three subjects has increased on the average by 11.3% (150 ± 17.3 vs 167 ± 6.7 H) and at one has decreased for 9.6% (155 vs 140 H).

Architectural characteristics

After DI, in the passive condition, L_f in the MG, and LG, and SOL has decreased for 12 (from 32 ± 2 to 28 ± 1 mm), 13 (from 36 ± 2 to 31 ± 2 mm), and 13% (from 36 ± 3 to 32 ± 2 mm) but in the active condition by 18 (from 26 ± 3 to 22 ± 2 mm), 22 (from 36 ± 3 to 28 ± 2 mm), and 21% (from 32 ± 2 to 26 ± 2 mm), respectively. The Θ_f , in the passive condition, was decreased by 22, 20 and 16%; but in the active condition by 17, 22 and 17 %, respectively.

Shorter fascicle lengths and steeper fascicle angles in the active compared with the passive condition show internal shortening of fascicles by contraction. Before DI ΔL_{muscle} the MG has found 7.9 mm after has decreased and has made 7.8 mm, and in Sol 5.9 vs 5.6 mm. Significant increase in ΔL_{muscle} from 0.9 to 3.3 mm were found by LG.

Discussion

This study describes, for the first time, the architecture of the human TS [medial (MG) and lateral (LG) gastrocnemius and soleus (SOL) muscles] *in vivo*, both at rest and after 7 days of unloading with exercise countermeasures (NMES).

After 7 days of DI a considerable increased of MVC, was observed in the exercise (+11%) groups whereas absence of preventive actions results in reduction in MVC more than on 30% [14-16]. Internal architecture of the GM, and LG, and SOL muscles was altered and this was only partially prevented by exercise countermeasures. Both fascicle length and pennation angle were reduced after DI with NMES, this strongly suggests a loss of both in-series and in-parallel sarcomeres, respectively. The functional consequence of the decreased fascicle length was a reduced shortening during contraction. The loss of in-series sarcomeres would mean that this is likely to have implications both on the *force-length* and *force-velocity* relationships of the muscle [17]. The observation of a smaller pennation angle during contraction after DI with NMES will partially

compensate for the loss of force, because of a more efficient force transmission to the tendon. The reduced initial resting pennation angle probably, grows out reduction decreased tendon stiffness or of the muscle-tendon complex that finds confirmation in substantial growth ΔL_{muscle} of LG (with 0.9 up to 3.3 mm after DI) during contraction. This observation is consistent with the findings of Kubo et al. [1]. A lower Θ_f observed after a simulated microgravity [6] partly compensates for the loss of force because the force transmission to the tendon becomes more efficient in spite of the decreased stiffness of the muscle-tendon complex [15,16].

The increase in the maximal voluntary torque after DI with NMES-training allows to assume, that NMES-training, apparently, promotes increase stream muscular afferentation [18] in conditions of his deficiency at gravitational unloading the muscular device caused long immersion that can promote also to the certain role in maintenance and normalization of activity of control systems by any movements (by a principle of a feedback). Tetanic electrical stimulation applied over human muscle generates contractions by depolarizing motor axons beneath the stimulating electrodes. However, the simultaneous depolarization of sensory axons can also contribute to the contractions by the synaptic recruitment of spinal motoneurons. Upon entering the spinal cord, the sensory volley recruits spinal motoneurons, leading to the development of central torque. This recruitment is consistent with the development of persistent inward currents in spinal motoneurons or interneurons [19,20]. Persistent inward currents lead to sustained depolarizations (plateau potentials), and it is becoming increasingly clear that they play an important role in regulating cell firing in normal [21,22]. Maximizing this central contribution may be beneficial for increased muscle force (by a principle of a feedback).

Conclusions, from the present results, follows, first, that the architecture different lead the triceps surae muscle considerably differs, reflecting, probably, their functional roles, second, various changes fibre length and pennation angle between different muscles, probably, are connected to distinctions in ability to develop force and elastic characteristics of sinews or muscle-tendon complex and, at last, in the third, NMES-training has preventive an effect on stimulated muscles: in part reduces loss of force of reduction of the muscles, the caused long unloading. The received data, allow concluding, that use of NMES-trained renders the expressed preventive action, essentially reduces depth and rate of atrophic processes in muscles.

Present results suggest that the structural adaptations to immersion (unloading) likely to contribute to a reduced force loss. On this background used NMES training of muscles in conditions of unloading allows to increase contractile function.

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Disclosures

No conflicts of interest, financial or otherwise, are declared by the author.

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